

ABSTRACT

5 A compliant link has a first member adapted to be connected to a linear actuator and a
second member adapted to be connected to a component to be moved by the linear
actuator, said members being interconnected by a connecting rod which is moveable
relative to both the first and second members, springs acting between the first and
10 second members and the connecting rod to oppose relative movement between the
connecting rod and the first and second members when an axial load below a first
predetermined value is applied to one of the members.